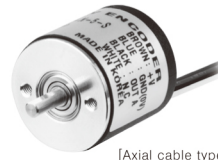


Diameter ø18mm Shaft type Incremental Rotary Encoder

■ Features

- Diameter ø18mm of miniature and weight 10g of ultra-light rotary encoder
- Easy installation at narrow space
- Small moment of inertia
- Power supply: 5VDC ±5%



[Axial cable type]



[Radial cable type]

NEW

■ Applications

- Suitable for office machine such as ATMs, bill counters, copy machines

Please read "Caution for your safety" in operation manual before using.



■ Ordering information

| E18S | 2.5 | 200 | 1 | N | 5 | R |
|----------------------------|--------------------------|----------------------|--------------|---|--------------|---|
| Series | Shaft diameter | Pulse/1Revolution | Output phase | Output | Power supply | Cable |
| Diameter ø18mm, shaft type | 2 : ø2mm 2.5 : ø2.5mm | 100, 200, (300, 400) | 1 : A | N: NPN open collector output V: Voltage output | 5 : 5VDC ±5% | R: Axial cable type S: Radial cable type |

■ Specifications

| | | | | |
|--------------------------|---|---|--|---|
| Item | | Diameter ø18mm shaft type of incremental rotary encoder | | |
| Resolution (P/R) | | 100, 200, (300, 400) (not indicated resolutions are customizable) | | |
| Electrical specification | Output phase | | A phase | |
| | Control output | NPN open collector output | Load current: Max. 30mA, Residual voltage: Max. 0.4VDC | |
| | | Voltage output | Load current: Max. 10mA, Residual voltage: Max.0.4VDC | |
| | Response time (rise/fall) | NPN open collector output | Max. 1µs | • Measuring condition- Cable length: 1m, I sink=Max. 20mA |
| | | Voltage output | Max. 1µs | |
| | Max. response frequency | | 25kHz | |
| | Power supply | | 5VDC ±5%(ripple P-P: max. 5%) | |
| | Current consumption | | Max. 50mA (disconnection of the load) | |
| | Insulation resistance | | Min. 100MΩ(at 500VDC megger between all terminals and case) | |
| | Dielectric strength | | 500VAC 50/60Hz for 1 min.(between all terminals and case) | |
| Connection | | Cable type(axial cable, radial cable) | | |
| Mechanical specification | Starting torque | | Max. 10gf·cm(10×10^{-4} N·m) | |
| | Moment of inertia | | Max. 0.5g·cm ² (5×10^{-6} kg·m ²) | |
| | Shaft loading | | Radial : 200gf, Thrust : 200gf | |
| | Max. allowable revolution ^{*1} | | 6000rpm | |
| Vibration | | 1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours | | |
| Shock | | Max. 50G | | |
| Environment | Ambient temperature | -10 to 70°C, storage: -20 to 80°C | | |
| | Ambient humidity | 35 to 85%RH, storage: 35 to 90%RH | | |
| Protection | | IP50(IEC standard) | | |
| Cable | | ø0.98mm, 4-wire, Length: 150mm, flat ribbon cable (AWG26, Core diameter: 0.16mm, Number of cores: 7, Insulator out diameter: ø0.98mm) | | |
| Accessory | | ø2mm coupling(supplied only for ø2mm shaft diameter model) | | |
| Approval | | CE | | |
| Unit weight | | Approx. 34.2g(approx. 12g) ^{*2} / Accessory: Approx. 1.2g | | |

*1: Make sure that. Max response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

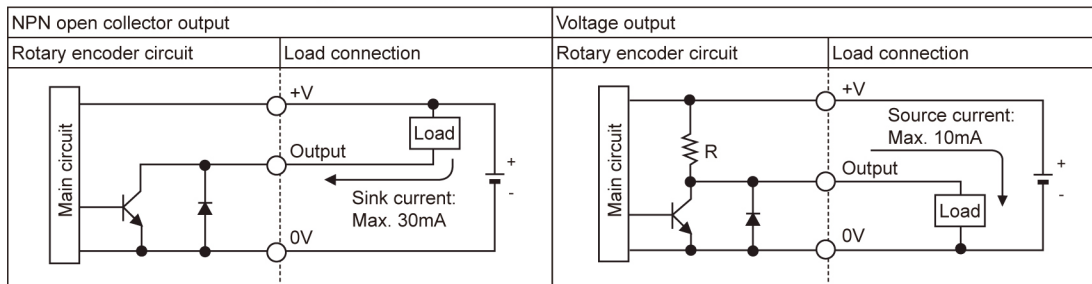
$$[\text{Max. response revolution}(\text{rpm}) = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}]$$

*2: The weight with packaging and the weight in parentheses is only unit weight.

*Environment resistance is rated at no freezing or condensation.

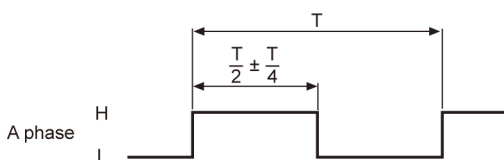
Incremental ø18mm Shaft type

Control output diagram



Output waveform

- NPN open collector output / Voltage output

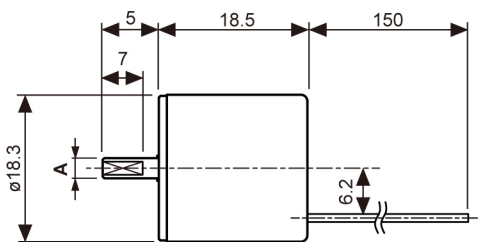
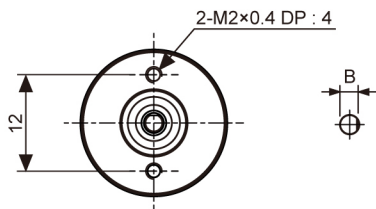


Connections



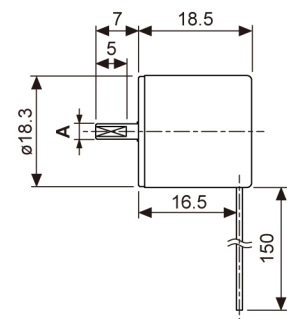
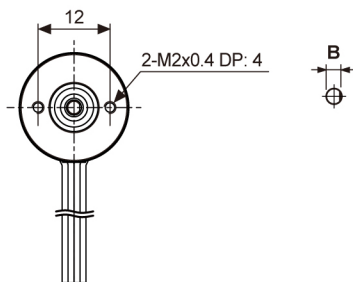
Dimensions

- ◎ Axial cable type



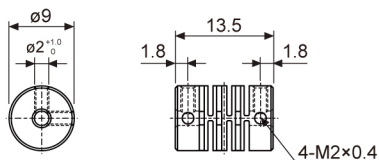
(unit : mm)

- ◎ Radial cable type



| Model | A | B |
|----------|---|-----|
| E18S-2 | Ø2.0 ^{+0.004} _{-0.02} | 1.7 |
| E18S-2.5 | Ø2.5 ^{+0.004} _{-0.02} | 2.2 |

- Coupling(E18S)



- Parallel misalignment: Min. 0.15mm
- Angular misalignment: Min. 2°
- End-play: Min. 0.2mm

※ For terminology of parallel, angular misalignment, and end-play, refer to the F-77 page.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other